

# Interferometry: I. Basic Concepts

## Incident Field:

The incident radiation from the sky is a function of the direction ( $\xi$ ) and of time ( $t$ ). The electric field of this radiation  $E(\xi, t)$  can be expressed in terms of the spatial frequency spectrum  $e(u, t)$  by

$$E(\xi, t) = \int_{-\infty}^{+\infty} e(u, t) e^{i2\pi\xi u} du$$

The inverse FT with respect to  $\xi$  and  $u$  gives

$$e(u, t) = \int_{-\infty}^{+\infty} E(\xi, t) e^{-i2\pi\xi u} d\xi$$

## Source Coherence Function:

$$\begin{aligned}\gamma(\xi_1, \xi_2, \tau) &= \lim_{T \rightarrow \infty} \frac{1}{2T} \int E_T(\xi_1, t) E_T^*(\xi_2, t - \tau) dt \\ &= \langle E_T(\xi_1, t) E_T^*(\xi_2, t - \tau) \rangle\end{aligned}$$

where  $E(\xi, t)$  = E field at source position  $\xi$ .

“cross correlation of signals received from two different points on the source at two different times.”

- If  $\xi_1 = \xi_2 = \xi$ ,  
$$\gamma(\xi, \tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int E_T(\xi, t) E_T^*(\xi, t - \tau) dt$$
 [“auto-correlation function towards  $\xi$ ”]
- If  $\tau = 0$ ,  $\gamma(\xi, 0) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int |E_T(\xi, t)|^2 dt$  [“average brightness towards  $\xi$ ”]

Normalized source coherence function:

$$\gamma_N(\xi_1, \xi_2, \tau) = \frac{\gamma(\xi_1, \xi_2, \tau)}{\sqrt{\gamma(\xi_1, 0)\gamma(\xi_2, 0)}}$$

## Spatial Coherence Function:

$$\Gamma(u_1, u_2, \tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int e_T(u_1, t) e_T^*(u_2, t - \tau) dt$$
$$= \langle e_T(u_1, t) e_T^*(u_2, t - \tau) \rangle$$

$u \equiv$  spatial coordinate in  $\lambda$ , normal to  $\xi = 0$

$$e(u, t) = \int_{-\infty}^{+\infty} E(\xi, t) e^{-i2\pi u \xi} d\xi$$

Because of this F.T. relation,

$$\Gamma(u_1, u_2, \tau) = \iint \gamma(\xi_1, \xi_2, \tau) e^{-i2\pi(u_1 \xi_1 - u_2 \xi_2)} d\xi_1 d\xi_2$$

## Completely Incoherent Source:

$$\langle E_T(\xi_1) E_T^*(\xi_2) \rangle = 0 \text{ for } \xi_1 \neq \xi_2$$

$$\gamma(\xi_1, \xi_2, \tau) = \gamma(\xi_1, \tau) \delta(\xi_1 - \xi_2)$$

$$\Gamma(u, \tau) = \int_{-\infty}^{+\infty} \gamma(\xi, \tau) e^{-i2\pi u \xi} d\xi$$

where  $u = u_1 - u_2$  and  $\xi = \xi_1 - \xi_2$

At  $\tau = 0$ ,  $\gamma(\xi, 0) = \langle |E_T(\xi)|^2 \rangle$  and

$$\Gamma(u, 0) = \int_{-\infty}^{+\infty} \langle |E_T(\xi)|^2 \rangle e^{-i2\pi u \xi} d\xi$$

**“van Cittert-Zernike Theorem”**

## Inverting the Measurement Equation

$\vec{S}_0$  = phase reference position = (0, 0, 1)

$\vec{S}$  = source position =  $(\xi, \eta, \sqrt{1 - \xi^2 - \eta^2})$

$\vec{B}_\lambda$  = (u, v, w) = baseline vector

$\vec{\sigma} = \vec{S} - \vec{S}_0 = (\xi, \eta, \sqrt{1 - \xi^2 - \eta^2} - 1)$

“visibility”:  $V(u, v, w) \equiv \Gamma(u, \tau = 0)$   
 $= \iint I(\xi, \eta) e^{-i2\pi(\vec{B}_\lambda \cdot \vec{\sigma})} d\Omega$

$$\vec{B}_\lambda \cdot \vec{\sigma} = (u\xi + v\eta + w\sqrt{1 - \xi^2 - \eta^2} - 1)$$
$$d\Omega = \frac{d\xi d\eta}{\sqrt{1 - \xi^2 - \eta^2}}$$

$$V(u, v, w) = \iint \frac{I(\xi, \eta)}{\sqrt{1 - \xi^2 - \eta^2}} e^{-i2\pi(u\xi + v\eta + w[\sqrt{1 - \xi^2 - \eta^2} - 1])} d\xi d\eta$$

This is **NOT** a Fourier Transform!!

## Limiting Case:

If source extent is limited to a small area around  $\vec{S}_0$  so that  $\vec{S} \sim \vec{S}_0$ ,

$$\sqrt{1 - \xi^2 - \eta^2} - 1 \simeq -\frac{1}{2}(\xi^2 + \eta^2) \sim 0$$

$$\begin{aligned} V(u, v, w) &= \iint \frac{I(\xi, \eta)}{\sqrt{1 - \xi^2 - \eta^2}} e^{-i2\pi(u\xi + v\eta)} d\xi d\eta \\ &= V(u, v, 0) \end{aligned}$$

$$V(u, v) = \iint \frac{I(\xi, \eta)}{\sqrt{1 - \xi^2 - \eta^2}} e^{-i2\pi(u\xi + v\eta)} d\xi d\eta$$

$\Rightarrow$  This **IS** a 2-D Fourier Transform!

## Note:

$I(\xi, \eta)$  is real.  $V(u, v)$  is complex.

$$\begin{aligned} V(u, v) &= \int I(\vec{\sigma}) e^{-i2\pi(\vec{B}_\lambda \cdot \vec{\sigma})} d\Omega \\ &= \int I(\vec{\sigma}) \cos(2\pi \vec{B}_\lambda \cdot \vec{\sigma}) d\Omega \\ &\quad + i \int I(\vec{\sigma}) \sin(2\pi \vec{B}_\lambda \cdot \vec{\sigma}) d\Omega \end{aligned}$$

**Measure  $V(u, v) \Rightarrow$  Recover  $I(\vec{\sigma})$  using F.T.!**

## II. Practical Issues

### RF Interferometer:

cross-correlation output from the correlator:

$$r(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T V_1(t) V_2(t - \tau) dt$$

In general, for  $\tau_g = \vec{B} \cdot \vec{S}_0 / c$ ,

$$r(\tau_g) = A_0 \Delta\nu |V| \cos(2\pi \vec{B}_\lambda \cdot \vec{S}_0 - \phi_s)$$

- amplitude  $|V|$  relates to source strength
- phase  $\phi_s$  relates to source location wrto  $\vec{S}_0$
- antenna area  $A_0$  and bandwidth  $\Delta\nu$  are instrumental

Wiener-Khinchin relation:

$$\int_{-\infty}^{+\infty} r(\tau) e^{-i2\pi\nu\tau} d\tau = |H(\nu)|^2$$

$$\text{and } \int_{-\infty}^{+\infty} r(\tau) |H(\nu)|^2 e^{i2\pi\nu\tau} d\tau = r(\tau)$$

where  $H(\nu)$  is amplitude (voltage) response and  $|H(\nu)|^2$  is power spectrum (**instrumental band-pass**).

## Finite Bandwidth:

Real interferometers have finite bandwidths, and the correlator output is an integral over frequency.

$$\begin{aligned} V &= \int I_\nu \left[ \frac{1}{\Delta\nu} \int_{\nu_0 - \Delta\nu/2}^{\nu_0 + \Delta\nu/2} e^{-i2\pi\nu\tau_g} d\nu \right] d\Omega \\ &= \int I_\nu e^{-i2\pi\nu_0\tau_g} \frac{\sin(\pi\tau_g\Delta\nu)}{\pi\tau_g\Delta\nu} d\Omega \end{aligned}$$

**To avoid loss of amplitude (sensitivity), we must track delay.**

## Delay Tracking (“fringe stopping”):

- reduce “bandwidth smearing”
- 2-D FT requires  $\tau = 0$ 
  - remove instrumental delay offset  $\tau_i$
  - remove geometrical delay  $\tau_g$

## FOV and Resolution:

- Field of View =  $\lambda/D$

Example:  $\nu = 230$  GHz,  $D = 6$  m

$$FOV = \frac{3 \times 10^{10}}{(230 \times 10^9)(600)} = 2.2 \times 10^{-4} = 45''$$

- Resolution:  $\theta_{syn} \sim \lambda/B_{max}$

Example:  $\nu = 230$  GHz,  $B_{max} = 300$  m

$$\theta_{syn} = \frac{3 \times 10^{10}}{(230 \times 10^9)(300000)} = 4.3 \times 10^{-6} = 0.9''$$

## Sensitivity:

$$\sigma = \frac{2kT_{sys}}{\eta_q A \sqrt{N_A(N_A - 1)\tau\Delta\nu}}$$

Example:  $T_{sys} = 200$  K,  $N_A = 8$ ,  $A = \frac{\pi}{4}(600)^2$ ,  $\Delta\nu = 4$  GHz,  $\eta_q = 0.88$ ,  $\tau = 60$  seconds

$$\Rightarrow \sigma = 6 \text{ mJy in 1 minute}$$

## Baseline and uv-Coverage:

Standard sampling requirement applies: to “map” a source, sample the uv-space as fully as possible.

**uv-sampling function  $\Leftrightarrow$  PSF**

(i.e., poor uv-sampling limits deconvolution.)

- astronomical coordinate system fixed on source
- a fixed baseline rotates with Earth, and so does the projected baseline
  - $\Rightarrow$  a fixed baseline tracks an arc in uv-space
- since  $I(l, m)$  is real,  $V(-u, -v) = V^*(u, v)$ 
  - $\Rightarrow$  actually tracks two arcs in uv-space